

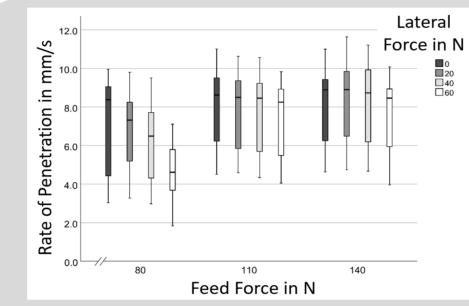
Karlsruhe Institute of Technology



Research Group: Human-Machine Systems (HMS)

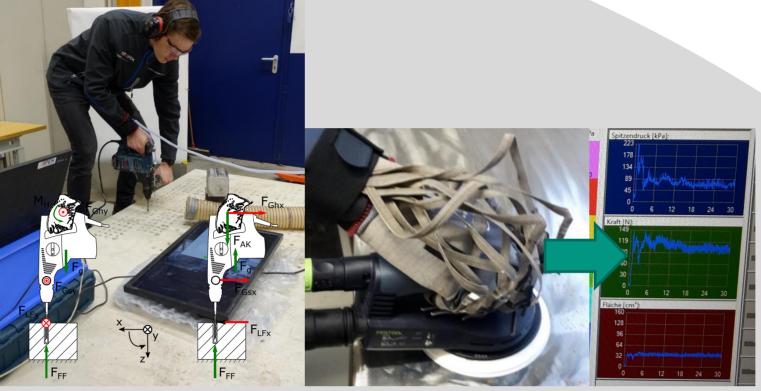
VISION

We analyze humans in their physical and informational interaction with technical systems based on valid measurands, represent them in human models, and integrate them into the product development process of human-machine systems.



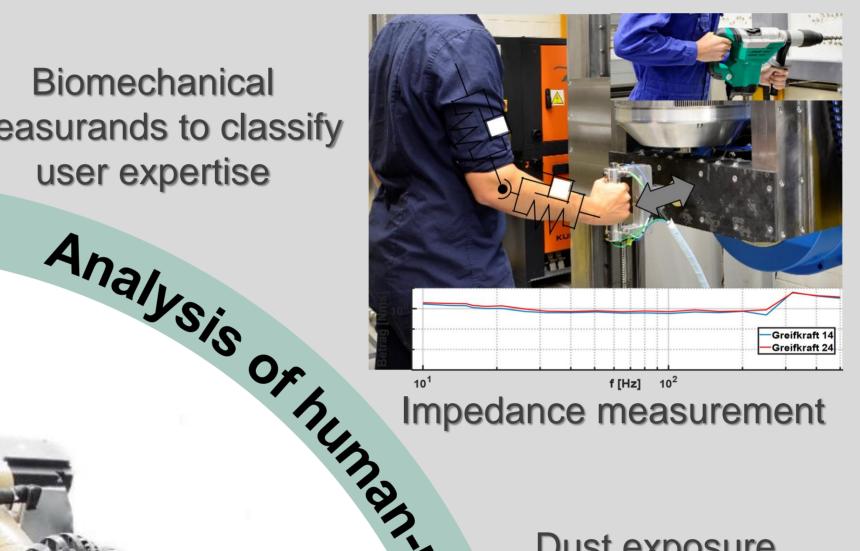
Relationship between real user behavior and the abrasion/ the productivity of a technical system

Tools for disruptive design changes for the reduction of the user stress



Force analysis for human-machine interaction





Comfort



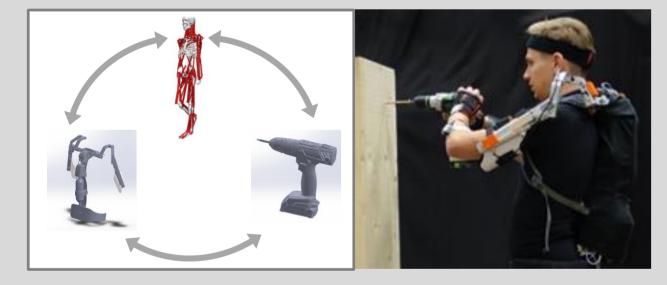


Development processes for intelligent user support



Identification of influences on the vibration exposure

Mixed reality environments for early validation of human-machine systems



Hybrid simulation models for user support systems such as exoskeletons

Design guidelines for optimized handle design



Dust exposure measurement Markerless human-motion-capturing Perceived Usabilit **Influencing Factors** luman Factors mental Factor Brand Influence Vibration

Grip Force

USE process for objective usability studies

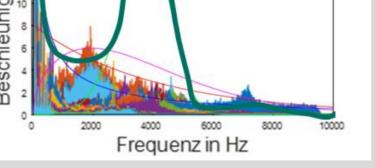
Acceptance studies for human-machine symbiosis

Profiles for the user classification with biomechanical

measurands



Models of user forces and motions for automated robot test benches



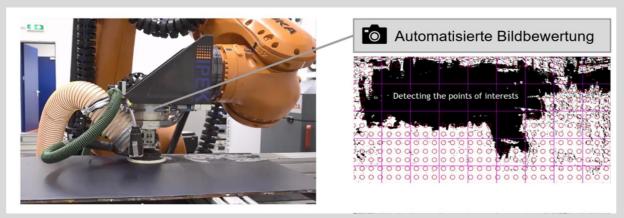
comfortindex

Perception models of vibration comfort



Mechanical models for the hand-arm vibration

Musculoskeletal models for user load assessment



Perception models for the working results

KIT – The Research University in the Helmholtz Association

